



Vibrator Auto-Guidance

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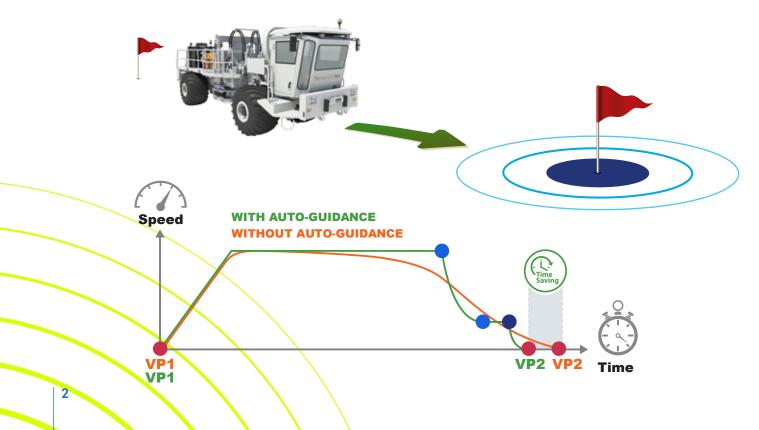
Auto-Guidance is a solution optimizing the vibrator move-up time between two VPs. Installed in the driver's cab and connected to the Nomad Central Command Unit, Auto-Guidance is able to take over control of the vehicle speed and baseplate commands. Using the vehicle's real time GPS position and that of the next "target" VP, Auto-Guidance computes and implements the most efficient deceleration profile towards the target and anticipates the baseplate down command.



Up to 10% increased productivity

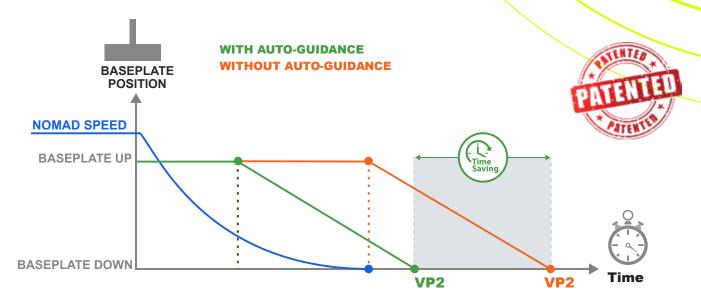
Optimize the travel time between two VPs

The approach phase is the most critical, too low a speed impacts productivity whereas too high a speed risks missing the surveyed VP position. With the Auto-Guidance, the speed is calculated to optimally position the Nomad in the absolute shortest time without any influence from the driver.



Reducing the baseplate dead time

The full control of the Nomad deceleration has been made possible by the development of new software algorithms. These allow for an advanced downward deployment of the baseplate avoiding dead time that on high production crews can be quite significant. The Auto-Guidance also guarantees that the vehicle is stopped before the baseplate touches the ground.



Better Data Quality

By ensuring that the Nomad is consistently positioned with a high degree of accuracy (typically within 1m of the surveyed position), the Vibrator Auto-Guidance also contributes to achieving the highest possible final data quality.



Improved HSE

With the Auto-Guidance solution, the driver need only keep his foot on the throttle during the decelaration phase, the Nomad speed will be controlled and adjusted automatically.

- Driver fatigue is reduced as less throttle and brake manipulation is required.
- With speed managed automatically, the driver has more time to focus on the environment reducing the risks of external hazards.



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Produced according to the Sercel environmental printing standard



